

Higher Categories, Complete Segal Spaces and the Cobordism Hypothesis

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A note on notation I try to denote usual categories with italic letters, and higher categories (2-categories, (∞, n) -categories, etc.) with calligraphic letters.

1 Extending $\mathbf{Cob}(n)$

1.1 Extending down

We've seen that the cobordism categories $\mathbf{Cob}(n)$ should really have more structure than just categories. In particular we should have, for every integer $k \leq n$,

a k -category¹ $\mathbf{Cob}_k(n)$ with

objects \longleftrightarrow closed oriented $(n - k)$ -manifolds
1-morphisms \longleftrightarrow oriented cobordisms
2-morphisms \longleftrightarrow cobordisms between cobordisms
 \vdots
 k -morphisms \longleftrightarrow (diffeomorphism classes of) n -manifolds with corners

We'd like to have a nice definition of k -category that includes $\mathbf{Cob}_k(n)$. Here's an obvious definition to make:

Definition 1.1.1. A **strict 1-category** is a category. A **strict k -category** is defined inductively as a category enriched over strict $(k - 1)$ -categories.

This definition is not the correct one. In particular $\mathbf{Cob}_k(n)$ is not a strict k -category since composition is not strictly associative, only associative up to isomorphism. We could adjust the definition of $\mathbf{Cob}_k(n)$ so that composition does become strictly associative, but this quickly gets messy.

Moral 1.1.2. We're going to need a better notion of k -category, where composition need only be associative up to isomorphism.

1.2 Extending up

Let's suppose we have a good definition of what a k -category is. Then we can define a (k, n) -category to be a k -category where all of the i -morphisms are invertible for $n < i \leq k$.

Example 1.2.1. A $(1, 0)$ -category should just be a groupoid.

It's also often useful to allow $k = \infty$; in fact we're going to define (∞, n) -categories later. This gives us a definition of (k, n) -categories simply by ignoring the morphisms above level k .

Example 1.2.2. An $(\infty, 0)$ -category is an ∞ -**groupoid**. Given a topological space X , we can form an ∞ -groupoid $\pi_{\leq \infty}(X)$ called the **fundamental ∞ -**

¹In this section we'll treat higher categories at an informal level. Note that the concept of a " k -category" has not been defined!

groupoid of X , with

objects \longleftrightarrow points of X
 1-morphisms \longleftrightarrow paths between points
 2-morphisms \longleftrightarrow homotopies between paths
 3-morphisms \longleftrightarrow homotopies between homotopies
 \vdots

The fundamental groupoid of X remembers all of X up to weak homotopy equivalence. More formally, the fundamental groupoid construction is an equivalence between topological spaces (up to weak homotopy equivalence) and ∞ -groupoids (up to equivalence). This assertion is known as the **homotopy hypothesis**². This allows us to think of $(\infty, 0)$ -categories as really being topological spaces. So as well as generalising category theory, higher category theory should also generalise topology.

Recall that in defining $\mathbf{Cob}(n)$, we defined a morphism $M \rightarrow N$ to be a diffeomorphism class of (oriented) cobordisms $M \rightarrow N$. Instead of considering two diffeomorphic cobordisms to be the same map, we could say that they differ by an invertible 2-morphism. Hence we should have an $(\infty, 1)$ -category $\mathbf{Cob}^b(n)$ with

objects \longleftrightarrow closed oriented $(n - 1)$ -manifolds
 1-morphisms \longleftrightarrow oriented cobordisms
 2-morphisms \longleftrightarrow diffeomorphisms between cobordisms
 3-morphisms \longleftrightarrow isotopies between diffeomorphisms
 \vdots

Note that this definition allows us to keep track of the diffeomorphism groups of our cobordisms.

We can combine our two higher-categorical versions of $\mathbf{Cob}(n)$ into a single (∞, n) -category \mathbf{Bord}_n with

²This is not a theorem yet, since we don't have a definition of ∞ -groupoid. We could either **define** an ∞ -groupoid to be a topological space, or we could regard the homotopy hypothesis as being a condition that our models of higher categories need to satisfy.

objects \longleftrightarrow 0-manifolds
 1-morphisms \longleftrightarrow cobordisms between 0-manifolds
 2-morphisms \longleftrightarrow cobordisms between cobordisms
 \vdots
 n -morphisms \longleftrightarrow n -manifolds with corners
 $(n + 1)$ -morphisms \longleftrightarrow diffeomorphisms
 $(n + 2)$ -morphisms \longleftrightarrow isotopies between diffeomorphisms
 \vdots

Moral 1.2.3. We're going to need a good definition of (∞, n) -categories. Note that the disjoint union operation on 0-manifolds should turn \mathbf{Bord}_n into a symmetric monoidal (∞, n) -category.

1.3 Intuitive statement of the cobordism hypothesis

The cobordism hypothesis is stated in terms of **framed** cobordisms. This is a technical point and won't really concern us. Denote the (∞, n) -category of framed cobordisms by $\mathbf{Bord}_n^{\text{fr}}$.

If \mathcal{C} is a symmetric monoidal (∞, n) -category then consider the category of \mathcal{C} -valued fully extended framed TFTs: we can identify this category with the category $\mathbf{Fun}^{\otimes}(\mathbf{Bord}_n^{\text{fr}}, \mathcal{C})$ of symmetric monoidal functors from $\mathbf{Bord}_n^{\text{fr}}$ to \mathcal{C} .

The cobordism hypothesis more or less says that the evaluation functor $Z \mapsto Z(*)$ determines a bijection between isomorphism classes of \mathcal{C} -valued fully extended framed TFTs and isomorphism classes of objects in \mathcal{C} satisfying suitable finiteness conditions.³

Remark 1.3.1. This specialises to a statement about $\mathbf{Cob}(n)$ by taking homotopy n -categories.

2 $(\infty, 1)$ -categories as complete Segal spaces

We'll first define $(\infty, 1)$ -categories and then soup up our definition in § 3 to get to (∞, n) -categories.

³By 'suitable finiteness conditions' we mean **full dualisability**, which we'll see a definition of in § 5. In \mathbf{Vect}_k the fully dualisable objects are exactly the finite-dimensional vector spaces.

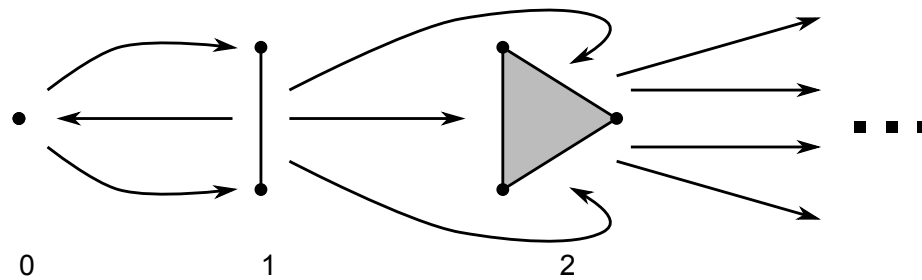
Intuitively, an $(\infty, 1)$ -category should be a **topological category**; one where the hom-sets have the structure of topological spaces.⁴ Higher morphisms are homotopies, homotopies between homotopies, and so on. However, while intuitive, this definition is very difficult to work with.

There are several other models⁵ but we're going to use **complete Segal spaces** as our models for $(\infty, 1)$ -categories since they generalise easily to (∞, n) -categories.

2.1 Preliminary: simplicial sets

Definition 2.1.1. The **simplex category** Δ has objects $[n] = \{0, 1, \dots, n\}$ and morphisms the weakly order-preserving maps.

It looks like



where we've omitted the maps from $[2]$ to $[1]$. The maps going to the right are the **face maps** and the maps going to the left are the **degeneracy maps**.

Definition 2.1.2. A **simplicial object** in a category C is a functor $\Delta^{\text{op}} \rightarrow C$. More concretely a simplicial object is a collection of objects X_n indexed by the positive integers together with various face and degeneracy maps.

Definition 2.1.3. A **morphism** between two simplicial objects $F : \Delta^{\text{op}} \rightarrow C$ and $G : \Delta^{\text{op}} \rightarrow C$ is a natural transformation $F \rightarrow G$. Concretely, a morphism of simplicial objects is a collection of maps $X_n \rightarrow Y_n$ commuting with the face and degeneracy maps.

Proposition 2.1.4. *The collection of simplicial objects in a category C and their morphisms itself forms a category, which we denote sC .*

A simplicial object X_\bullet looks like

$$X_0 \begin{array}{c} \leftarrow \\ \rightleftarrows \\ \rightarrow \end{array} X_1 \begin{array}{c} \leftarrow \\ \rightleftarrows \\ \rightarrow \end{array} X_2 \begin{array}{c} \leftarrow \\ \rightleftarrows \\ \rightarrow \end{array} \cdots$$

⁴One way to think about this is that an $(\infty, 1)$ -category should be enriched in $(\infty, 0)$ -categories, which are the same thing as topological spaces.

⁵A good account of these are given in [8].

We'll be interested in **simplicial sets**; simplicial objects in **Set**.⁶ Later we'll be interested in simplicial topological spaces.

Example 2.1.5. Given a topological space X , we can define (functorially) a simplicial set $\text{Sing}(X)$ that at level n is the set $\text{Hom}(\Delta^n, X)$ of maps from the n -simplex $\Delta^n \subseteq \mathbb{R}^{n+1}$ to X . We also have a geometric realisation functor $|\cdot| : s\mathbf{Set} \rightarrow \mathbf{Top}$ and in fact $|\text{Sing}(X)|$ is weakly homotopy equivalent to X . Simplicial sets are good combinatorial models of topological spaces.⁷

Example 2.1.6. Given a category C , the **nerve** is a simplicial set $N(C)$ which at level n consists of the strings $C_0 \xrightarrow{f_1} C_1 \xrightarrow{f_2} \dots \xrightarrow{f_n} C_n$ of n composable morphisms. It's possible to recover C up to isomorphism from its nerve $N(C)$.

We might wonder what simplicial sets are the nerves of categories.

Proposition 2.1.7 (the Nerve Theorem). *A simplicial set X is isomorphic to the nerve of a category if and only if for all $m, n \geq 0$ the diagram*

$$\begin{array}{ccc} X_{m+n} & \longrightarrow & X_m \\ \downarrow & & \downarrow \\ X_n & \longrightarrow & X_0 \end{array}$$

induced by the maps

$$0 < 1 < \dots < m \longleftarrow 0 < 1 < \dots < m$$

$$\begin{array}{ccccc} m < m+1 < \dots < m+n & & [m+n] & \longleftarrow & [m] & & m \\ & & \uparrow & & \uparrow & & \uparrow \\ & & 0 < 1 < \dots < n & & [n] & \longleftarrow & [0] & & 0 \\ & & & & & & & & & \\ & & & & 0 & \longleftarrow & 0 & & & \end{array}$$

is Cartesian (i.e. a pullback diagram).

Whenever this diagram appears, we will fix the convention that the maps featuring are the maps described above.

2.2 Homotopy theory

Our philosophy is that $(\infty, 1)$ -category theory should be category theory, but done in a homotopy-theoretic manner. This is because an $(\infty, 1)$ -category is just a topological category where the higher morphisms are given by homotopies.

⁶A simplicial set is the same thing as a presheaf on Δ .

⁷Technically $s\mathbf{Set}$ and \mathbf{Top} are Quillen equivalent (via these two functors), so they have the same homotopy theory.

Since Proposition 2.1.7 tells us that we can recover a category from its nerve, we'll try to code up the concept of a nerve in homotopy theory. We'll see that a Segal space is precisely this concept of 'homotopy nerve'. However we'll see that a Segal space alone won't quite be enough to recover an $(\infty, 1)$ -category: we'll need some more conditions.

Definition 2.2.1. Let $X \xrightarrow{f} Z \xleftarrow{g} Y$ be a diagram of topological spaces⁸ and continuous maps. The **homotopy fibre product** $X \times_Z^h Y$ of X and Y along f and g is the space $X \times_Z Z^{[0,1]} \times_Z Y$ whose points are triples (x, y, p) with $x \in X$, $y \in Y$ and $p : [0, 1] \rightarrow Z$ a path in Z from $f(x)$ to $g(y)$.

Remark 2.2.2. There is a canonical map from $X \times_Z Y$ to $X \times_Z^h Y$ given by $(x, y) \mapsto (x, y, p)$ where p is the constant path from $f(x) = g(y)$ to itself.

Example 2.2.3. Let X be a space and $p : * \rightarrow X$ be the inclusion of a basepoint. Then the homotopy fibre product of $* \xrightarrow{p} X \xleftarrow{p} *$ is the space ΩX of loops in X based at p . The usual fibre product is the one point space $*$.

Example 2.2.4. The homotopy fibre product of $* \xrightarrow{p} Y \xleftarrow{f} X$ is the homotopy fibre of f over the basepoint p in Y .

The usual fibre product of topological spaces does not respect homotopy equivalences. The homotopy fibre product is invariant under homotopy equivalence: if we replace f and g by homotopic maps then the weak homotopy type of $X \times_Z^h Y$ does not change.

Remark 2.2.5. Another nice property of the homotopy fibre product is that we have a long exact sequence of homotopy groups

$$\cdots \rightarrow \pi_n(X \times_Z^h Y) \rightarrow \pi_n(X) \times \pi_n(Y) \rightarrow \pi_n(Z) \rightarrow \cdots \rightarrow \pi_0(X) \times \pi_0(Y)$$

Proposition 2.2.6. *The homotopy fibre product $X \times_Z^h Y$ comes with two canonical projection maps to X and Y making the diagram*

$$\begin{array}{ccc} X \times_Z^h Y & \longrightarrow & Y \\ \downarrow & & \downarrow \\ X & \longrightarrow & Z \end{array}$$

commute up to canonical homotopy. Moreover if the square

$$\begin{array}{ccc} W & \longrightarrow & Y \\ \downarrow & & \downarrow \\ X & \longrightarrow & Z \end{array}$$

*is homotopy commutative then there is a unique up to homotopy map $W \rightarrow X \times_Z^h Y$ making the two triangles obtained strictly commutative. For this reason we often call $X \times_Z^h Y$ the **homotopy pullback** of X and Y along f and g .*

⁸For technical reasons we need to work with a 'convenient category' of spaces. For example we can use CGH (compactly generated Hausdorff) spaces as in [5] or CGWH (compactly generated weak Hausdorff) spaces as in [6]. For concreteness we may suppose that all topological spaces are CGWH.

Definition 2.2.7. A homotopy commutative square

$$\begin{array}{ccc} W & \longrightarrow & Y \\ \downarrow & & \downarrow \\ X & \longrightarrow & Z \end{array}$$

is **homotopy Cartesian** (or just **h-Cartesian**) if there is a weak homotopy equivalence $W \rightarrow X \times_{X_0}^h Y$ such that the triangles obtained are strictly commutative.

Neither

$$\text{h-Cartesian} \implies \text{Cartesian}$$

nor

$$\text{Cartesian} \implies \text{h-Cartesian}$$

is true in general! If our maps are sufficiently nice (e.g. if $X \rightarrow Z$ is a fibration) then a Cartesian square is homotopy Cartesian. In this situation we can compute the homotopy fibre product by computing the usual fibre product.

2.3 Segal spaces

Definition 2.3.1 (Rezk). A simplicial topological space X_\bullet is a **Segal space** if for all $m, n \geq 0$ the diagram

$$\begin{array}{ccc} X_{m+n} & \longrightarrow & X_m \\ \downarrow & & \downarrow \\ X_n & \longrightarrow & X_0 \end{array}$$

is h-Cartesian. We can equivalently specify that for all n the **Segal maps**

$$X_n \rightarrow \underbrace{X_1 \times_{X_0}^h X_1 \times_{X_0}^h \cdots \times_{X_0}^h X_1}_n$$

are weak homotopy equivalences.

Remark 2.3.2. This is not a universally accepted definition. Some authors, for example [2], specify in addition that X_\bullet should be **Reedy fibrant**, a ‘niceness’ condition on simplicial spaces that ensures that the homotopy pullback $X_m \times_{X_0}^h X_n$ is the usual pullback $X_m \times_{X_0} X_n$. In this case it’s enough to demand that $X_{m+n} \rightarrow X_m \times_{X_0} X_n$ is a weak homotopy equivalence. Reedy fibrancy is a technical condition that can always be satisfied. For more on model category theory and the definition of Reedy fibrancy, the reader can consult e.g. Appendix A.2 of [7].

What do Segal spaces have to do with $(\infty, 1)$ -categories? Let's suppose for the moment that we already have a good theory of $(\infty, 1)$ -categories. Just like a 1-category has an underlying groupoid, obtained by throwing away all of the noninvertible morphisms, an $(\infty, 1)$ -category should have an underlying ∞ -groupoid obtained in the same way:

Idea 2.3.3. Let \mathcal{C} be any $(\infty, 1)$ -category. We can loosely define the **underlying ∞ -groupoid** of \mathcal{C} , which I will denote $\pi_{\leq \infty}(\mathcal{C})$, to be the ∞ -groupoid with

$$\begin{aligned} \text{objects} &\longleftrightarrow \text{objects of } \mathcal{C} \\ \text{1-morphisms} &\longleftrightarrow \text{invertible 1-morphisms in } \mathcal{C} \\ \text{2-morphisms} &\longleftrightarrow \text{2-morphisms between invertible 1-morphisms of } \mathcal{C} \\ &\vdots \end{aligned}$$

Since we can identify ∞ -groupoids with topological spaces, we may think of $\pi_{\leq \infty}(\mathcal{C})$ as a topological space $B_0\mathcal{C}$ which we refer to as the **classifying space for objects of \mathcal{C}** . Note that by definition the fundamental ∞ -groupoid of $B_0\mathcal{C}$ is the underlying ∞ -groupoid of \mathcal{C} .

Clearly $B_0\mathcal{C}$ should not in general encode all of the information about \mathcal{C} . For example it doesn't know about noninvertible morphisms or how composition works. We can extend the above definition to get classifying spaces for n -morphisms of \mathcal{C} (since we can think of an object as a 0-morphism), and hopefully this collection of classifying spaces should allow us to recover \mathcal{C} .

Idea 2.3.4. Let $[n]$ be the 1-category associated to the ordered set $\{0, 1, 2, \dots, n\}$. Let \mathcal{C} be an $(\infty, 1)$ -category. We can think of an n -morphism in \mathcal{C} as a functor $[n] \rightarrow \mathcal{C}$. The collection $\text{Fun}([n], \mathcal{C})$ of functors $[n] \rightarrow \mathcal{C}$ itself naturally has the structure of an $(\infty, 1)$ -category, so it has an underlying ∞ -groupoid $\pi_{\leq \infty}(\text{Fun}([n], \mathcal{C}))$. Let $B_n\mathcal{C}$ be the topological space associated to this ∞ -groupoid. We call $B_n\mathcal{C}$ the **classifying space for n -morphisms in \mathcal{C}** . Again, by definition the fundamental ∞ -groupoid of $B_n\mathcal{C}$ is the underlying ∞ -groupoid of $\text{Fun}([n], \mathcal{C})$.

What kind of object should the collection $B_\bullet\mathcal{C}$ be? Moreover, to what extent does it determine \mathcal{C} ? The answer to the first question is that $B_\bullet\mathcal{C}$ should be a simplicial space, and moreover a Segal space. The Segal conditions formalise the idea that giving a chain

$$A_0 \rightarrow A_1 \rightarrow \dots \rightarrow A_{n+m}$$

of composable morphisms should be equivalent to giving two chains

$$A_0 \rightarrow \dots \rightarrow A_n \qquad A_n \rightarrow \dots \rightarrow A_{n+m}$$

and moreover that it should not matter where we break the chains. To answer the second question, we can try to define an 'inverse' to the operation $\mathcal{C} \rightarrow B_\bullet\mathcal{C}$ and see if we need to add any extra data to a general Segal space in order to extract an ∞ -category.

Idea 2.3.5. Given a Segal space X_\bullet we should be able to construct an $(\infty, 1)$ -category $\mathcal{C}(X_\bullet)$ which has

$$\begin{aligned} \text{objects} &\longleftrightarrow \text{points of } X_0 \\ \text{Mapping spaces } \text{Map}(x, y) &\longleftrightarrow \{x\} \times_{X_0}^h X_1 \times_{x_0}^h \{y\} \\ \text{composition law} &\longleftrightarrow \text{given by } X_2 \\ \text{higher associativity information} &\longleftrightarrow \text{given by } X_3, X_4 \dots \end{aligned}$$

Observe that the connected components of the space $\text{Map}(x, y)$ should be precisely the homotopy classes of 1-morphisms in $\mathcal{C}(X_\bullet)$. With this in mind, we can construct a 1-category from a Segal space:

Definition 2.3.6. The **homotopy category** hX_\bullet of a Segal space X_\bullet is the category whose objects are the points of X_0 , and whose homsets are

$$\begin{aligned} \text{Hom}_{hX_\bullet}(x, y) &:= \pi_0(\text{Map}(x, y)) \\ &= \pi_0(\{x\} \times_{X_0}^h X_1 \times_{x_0}^h \{y\}) \end{aligned}$$

Remark 2.3.7. The homotopy category of X_\bullet records some of the basic information about $\mathcal{C}(X_\bullet)$ - it knows what the objects should be, for example - but it forgets all of the homotopical information by identifying all homotopic maps. It can be thought of as a 1-categorical ‘flattening’ of the $(\infty, 1)$ -category $\mathcal{C}(X_\bullet)$.

2.4 Completeness

If we start with a general Segal space X_\bullet , how does it compare to the Segal space $Y_\bullet := B_\bullet(\mathcal{C}(X_\bullet))$? The fundamental groupoid of Y_0 is the classifying space for 0-morphisms of $\mathcal{C}(X_\bullet)$. This receives a map from the fundamental groupoid of X_0 but this map is not necessarily an equivalence, since there may be invertible 1-morphisms in $\mathcal{C}(X_\bullet)$ which do not come from paths in X_0 . We’d like to impose an extra condition on our Segal spaces which ensures that every invertible 1-morphism in $\mathcal{C}(X_\bullet)$ comes from an essentially unique path in X_0 .

Definition 2.4.1. Let p_i be the map from $[0]$ to $[1]$ given by $0 \mapsto i$. For any Segal space X_\bullet write $p_i^* : X_1 \rightarrow X_0$ for the map induced by p_i . If $f \in X_1$ then write $x := p_0^*(f)$ and $y := p_1^*(f)$ so that we can think of f as a path from x to y . The map $\{f\} \rightarrow \{x\} \times_{X_0} X_1 \times_{x_0} \{y\} \rightarrow \{x\} \times_{X_0}^h X_1 \times_{x_0}^h \{y\}$ determines an element $[f]$ of $\text{Hom}_{hX_\bullet}(x, y) = \pi_0(\{x\} \times_{X_0}^h X_1 \times_{x_0}^h \{y\})$. Say that f is **invertible** if $[f]$ is an isomorphism.

Example 2.4.2. If X_\bullet is a Segal space let $\delta : X_0 \rightarrow X_1$ be the map induced by the unique map $[1] \rightarrow [0]$. Then for every $x \in X_0$, the map $[\delta(x)]$ is the identity map id_x in the homotopy category. So $\delta(x)$ is invertible for every x .

Definition 2.4.3. If $Z \subseteq X_1$ is the subspace of invertible elements of a Segal space X_\bullet , then say that X_\bullet is **complete** if $\delta : X_0 \rightarrow Z$ is a weak homotopy equivalence.

So a complete Segal space is one where every isomorphism in $\mathcal{C}(X_\bullet)$ arises from an essentially unique path in X_0 . In fact, if X_\bullet is complete then we should have an equivalence $X_\bullet \cong B_\bullet(\mathcal{C}(X_\bullet))$.

Remark 2.4.4. If one is more careful and starts with a rigorous axiomatisation of $(\infty, 1)$ -categories then the above assertions and intuitive ideas can be turned into theorems. This was done by Toën in [9].

We've seen that the well-defined theory of complete Segal spaces should correspond to the as-yet-undefined theory of $(\infty, 1)$ -categories. With this in mind, we make the following rather bold definition:

Definition 2.4.5. An $(\infty, 1)$ -category is a complete Segal space.

Proposition 2.4.6 (Rezk). *Any Segal space X_\bullet has a completion; i.e. admits a homotopy universal morphism⁹ $X_\bullet \rightarrow Y_\bullet$ where Y_\bullet is complete. In general Y_\bullet is unique up to homotopy and we refer to it as the **completion** of X_\bullet , denoted \hat{X}_\bullet . The map $X_\bullet \rightarrow \hat{X}_\bullet$ is functorial.*

Remark 2.4.7. Complete Segal spaces are the fibrant objects of a suitable model structure on the category of simplicial spaces, just as quasicategories are the fibrant objects of the Joyal model structure on the category of simplicial sets.

3 (∞, n) -categories as n -fold complete Segal spaces

Now we have a definition of $(\infty, 1)$ -category as a certain functor $\Delta^{\text{op}} \rightarrow \mathbf{Top}$, we're going to generalise this and define an (∞, n) -category as a certain functor $(\Delta^{\text{op}})^{\times n} \rightarrow \mathbf{Top}$.

Definition 3.1.1. An n -fold simplicial object in a category C is a functor

$$\underbrace{\Delta^{\text{op}} \times \Delta^{\text{op}} \times \cdots \times \Delta^{\text{op}}}_n \rightarrow C$$

Example 3.1.2. A 0-fold simplicial object is an object. A 1-fold simplicial object is just a simplicial object in the usual sense.

In general an n -fold simplicial object in a category C is a collection $X_{i_1 \dots i_n}$ of objects of C indexed by n -tuples of nonnegative integers $\underline{i} = (i_1, \dots, i_n)$ along with a collection of face and degeneracy maps. We'll always use an underbar to denote multiindices in this manner. We think of n -fold simplicial objects as having n 'directions' in which to compose.

Definition 3.1.3. An n -fold simplicial space is an n -fold simplicial object in the category \mathbf{Top} .

⁹A morphism of Segal spaces is a morphism of the underlying simplicial spaces.

Definition 3.1.4. A map $X \rightarrow Y$ of n -fold simplicial spaces is a **weak homotopy equivalence** if all of the maps $X_{\underline{i}} \rightarrow Y_{\underline{i}}$ are weak homotopy equivalences.

Definition 3.1.5. A diagram

$$\begin{array}{ccc} W & \longrightarrow & Y \\ \downarrow & & \downarrow \\ X & \longrightarrow & Z \end{array}$$

of n -fold simplicial spaces is **homotopy Cartesian** if for all multiindices \underline{i} the square

$$\begin{array}{ccc} W_{\underline{i}} & \longrightarrow & Y_{\underline{i}} \\ \downarrow & & \downarrow \\ X_{\underline{i}} & \longrightarrow & Z_{\underline{i}} \end{array}$$

is homotopy Cartesian.

Definition 3.1.6. An n -fold simplicial space X is **essentially constant** if it's weakly homotopy equivalent to a constant n -fold simplicial space.

Via currying, whenever $n > 0$ we can always think of an n -fold simplicial object in C as a simplicial object in the category of $(n - 1)$ -fold simplicial objects in C . This idea will form the basis of our inductive definition of an n -fold complete Segal space.

Definition 3.1.7. For $n > 0$ an n -fold simplicial space X , thought of as a simplicial object in the category of $(n - 1)$ -fold simplicial spaces, is said to be an **n -fold Segal space** if the following conditions are met:

- i) Every X_k is an $(n - 1)$ -fold Segal space.
- ii) For all m and l the diagram

$$\begin{array}{ccc} X_{m+l} & \longrightarrow & X_m \\ \downarrow & & \downarrow \\ X_l & \longrightarrow & X_0 \end{array}$$

is a homotopy Cartesian square of $(n - 1)$ -fold simplicial spaces.

- iii) X_0 is an essentially constant $(n - 1)$ -fold simplicial space.

Moreover, we say that an n -fold Segal space is **complete** if

- iv) Each X_k is a complete $(n - 1)$ -fold Segal space.
- v) The Segal space $Y_{\bullet} = X_{\bullet,0,0,\dots,0}$ is complete.

Definition 3.1.8. An (∞, n) -**category** is a complete n -fold Segal space.

Proposition 3.1.9. *Any n -fold Segal space has a completion.*

Loosely, an n -fold complete Segal space is a ‘fattened’ or ‘spread out’ version of an (∞, n) -category. Some illuminating diagrams are given in §2.2.1 of [2].

4 The (∞, n) -category \mathbf{Bord}_n

In this section we’ll code up our ideas about \mathbf{Bord}_n to define an n -fold simplicial space \mathbf{PBord}_n . We’ll indicate how this is an n -fold Segal space that in general is not complete. Then we can define the (∞, n) -category \mathbf{Bord}_n to be the completion $\widehat{\mathbf{PBord}_n}$ of \mathbf{PBord}_n . Our exposition will be fairly informal; for a more rigorous explanation see §2 of [2].

4.1 The level sets $(\mathbf{PBord}_n^V)_{\underline{k}}$

We want to think of $(\mathbf{PBord}_n)_{(k_1, \dots, k_n)}$ as a collection of $k_1 k_2 \cdots k_n$ composed cobordisms, with k_i cobordisms in the i^{th} direction.

Idea 4.1.1. Cobordisms are easier to deal with when we consider them as submanifolds of some large \mathbb{R}^m . So we’ll define sets of cobordisms living in \mathbb{R}^m for varying m , and then take a limit over m . Whitney’s embedding theorem will ensure that we get all of the cobordisms, since every l -dimensional manifold can be embedded in \mathbb{R}^{2l} .

Definition 4.1.2. Let V be a finite-dimensional real vector space and fix a multiindex $\underline{k} = (k_1, \dots, k_n)$. Define $(\mathbf{PBord}_n^V)_{\underline{k}}$ to be the set of tuples

$$(M, (t_0^i, \dots, t_{k_i}^i)_{i=1 \dots n})$$

satisfying the following:

- i) For each $1 \leq i \leq n$, $t_0^i \leq \dots \leq t_{k_i}^i$ is an ordered tuple of $k_i + 1$ real numbers.
- ii) M is a closed n -dimensional submanifold of $V \times \mathbb{R}^n$ and the composition $\pi : M \hookrightarrow V \times \mathbb{R}^n \rightarrow \mathbb{R}^n$ is proper¹⁰.
- iii) For a subset S of $\{1, \dots, n\}$ let $p_S : M \rightarrow \mathbb{R}^S$ denote the composition $M \xrightarrow{\pi} \mathbb{R}^n \rightarrow \mathbb{R}^S$. Then we require that for every $1 \leq i \leq n$ and every $0 \leq j \leq k_i$, that for all $x \in p_{\{i\}}^{-1}(t_j^i)$, the map $p_{\{i, \dots, n\}}$ is submersive¹¹ at x .

Remark 4.1.3. What’s the motivation behind this definition? If we want to think of M as being a collection of composed cobordisms, the numbers t_j^i record the ‘cutting points’ where we glue two cobordisms together. So the region of M between the hyperplanes corresponding to t_j^i and t_{j+1}^i should be the $(j + 1)^{\text{st}}$ cobordism glued in the i^{th} direction.

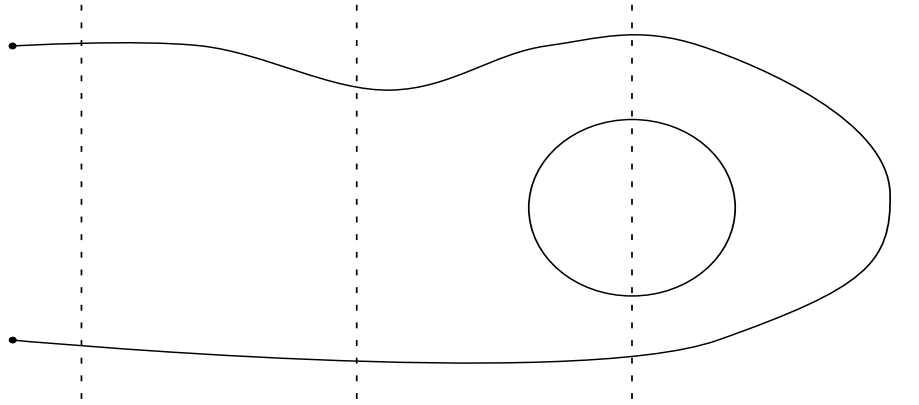
¹⁰A map is **proper** if preimages of compact sets are compact.

¹¹A map $f : M \rightarrow N$ is **submersive at** $m \in M$ if the differential $df_x : T_x M \rightarrow T_x N$ is surjective. A map is **submersive** if it’s submersive at every point of its domain.

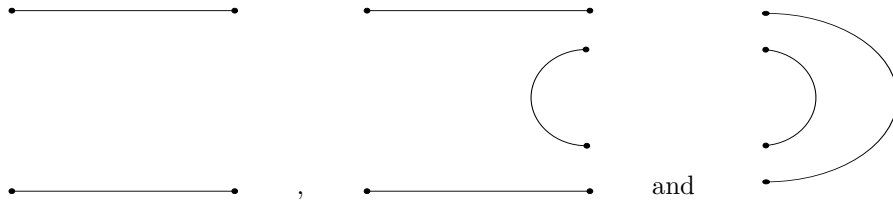
Condition iii) says that in particular the set $p_{\{n\}}^{-1}(t_j^n)$ is an $(n-1)$ -dimensional submanifold that we can think of as one of the $(n-1)$ -cobordisms that we glue together to get M .

Furthermore the set $p_{\{n-1,n\}}^{-1}\{t_{j_{n-1}}^{n-1}, t_{j_n}^n\}$ is an $(n-2)$ -dimensional manifold that is one of the $(n-2)$ -cobordisms joined by an $(n-1)$ -cobordism. Similarly, the preimage $p_{\{m,\dots,n\}}^{-1}\{t_{j_m}^m, \dots, t_{j_n}^n\}$ is an $(m-1)$ -dimensional manifold that we can loosely think of as one of our $(m-1)$ -morphisms.

Example 4.1.4. Here is an element of $\mathbf{PBord}_1^{\mathbb{R}}$:



The cutting points indicated by the dotted lines allow us to view this as a composition of the three 1-cobordisms



4.2 The topological spaces $(\mathbf{PBord}_n^V)_k$

Fact 4.2.1 ([10], Chapter II). The set $\text{Emb}(X, Y)$ of smooth embeddings of a smooth manifold X into a smooth manifold Y has a topology, the **Whitney C^∞ topology**.

Theorem 4.2.2 ([11]). *The space $\text{Sub}(V \times \mathbb{R}^n)$ of closed n -dimensional submanifolds of $V \times \mathbb{R}^n$ can be identified with the space*

$$\bigsqcup_{[L]} \text{Emb}(L, V \times \mathbb{R}^n) / \text{Diff}(L)$$

where the disjoint union is taken over diffeomorphism classes of n -dimensional manifolds L . Moreover the topology on $\text{Sub}(V \times \mathbb{R}^n)$ has neighbourhood basis at $M \subseteq V \times \mathbb{R}^n$ the sets

$$\{N \subseteq V \times \mathbb{R}^n : N \cap K = f(M) \cap K \text{ for all } f \in W\}$$

where K is a compact subset of $V \times \mathbb{R}^n$ and $W \subseteq \text{Emb}(M, V \times \mathbb{R}^n)$ is a neighbourhood (in the Whitney C^∞ topology) of the inclusion $M \hookrightarrow V \times \mathbb{R}^n$.

Remark 4.2.3. The space $\text{Sub}(V \times \mathbb{R}^n)$ is sometimes denoted by $\Psi(V \times \mathbb{R}^n)$.

Since we can view $(\mathbf{PBord}_n^V)_{\underline{k}}$ as a subset of $\text{Sub}(V \times \mathbb{R}^n) \times \mathbb{R}^k$, for some $k \in \mathbb{N}$ depending only on \underline{k} , we can give $(\mathbf{PBord}_n^V)_{\underline{k}}$ the subspace topology.

4.3 The n -fold simplicial space \mathbf{PBord}_n

Proposition 4.3.1. *There are face and degeneracy maps making the collection of spaces*

$$\left\{ (\mathbf{PBord}_n^V)_{\underline{k}} : \underline{k} \in \mathbb{N}^n \right\}$$

into an n -fold simplicial space.

Call this n -fold simplicial space \mathbf{PBord}_n^V . Loosely, the face maps forget a number t_j^i whereas the degeneracy maps repeat a number t_j^i .

Now we can remove the dependence on the vector space V . Let \mathbb{R}^∞ be the unique real vector space of countably infinite dimension. We define the n -fold simplicial space \mathbf{PBord}_n to be the limit

$$\mathbf{PBord}_n := \varinjlim_{V \subseteq \mathbb{R}^\infty} \mathbf{PBord}_n^V$$

4.4 The n -fold Segal spaces \mathbf{PBord}_n and \mathbf{Bord}_n

We need to verify that the n -fold simplicial space \mathbf{PBord}_n is in fact an n -fold Segal space. The important point is to prove that the Segal map

$$\begin{array}{ccc} (\mathbf{PBord}_n)_{k_1, \dots, k_i + k'_i, \dots, k_n} & & \\ \downarrow & & \\ (\mathbf{PBord}_n)_{k_1, \dots, k_i, \dots, k_n} & \times^h & (\mathbf{PBord}_n)_{k_1, \dots, k'_i, \dots, k_n} \\ & (\mathbf{PBord}_n)_{k_1, \dots, 0, \dots, k_n} & \end{array}$$

is a weak homotopy equivalence.

Fact 4.4.1. \mathbf{PBord}_n is nice enough for the homotopy fibre product above to be weakly homotopy equivalent to the usual fibre product. More technically, \mathbf{PBord}_n is Reedy fibrant - see 2.3.2 for further discussion.

Corollary 4.4.2. *To verify that the above Segal map is a weak homotopy equivalence, we may replace the homotopy fibre product with the genuine fibre product of topological spaces.*

Replacing the homotopy pullback with the usual pullback, we see that an element of

$$(\mathbf{PBord}_n)_{k_1, \dots, k_i, \dots, k_n} \times_{(\mathbf{PBord}_n)_{k_1, \dots, 0, \dots, k_n}} (\mathbf{PBord}_n)_{k_1, \dots, k'_i, \dots, k_n}$$

is a pair of submanifolds M and N of $V \times \mathbb{R}^n$ for some V , together with data allowing us to glue them on their intersection. Gluing them together gets us an element of $(\mathbf{PBord}_n)_{k_1, \dots, k_i + k'_i, \dots, k_n}$. The Segal map is in fact a homeomorphism, not just a homotopy equivalence. We can now deduce the following:

Theorem 4.4.3. \mathbf{PBord}_n is an n -fold Segal space.

The n -fold Segal space \mathbf{PBord}_n is not in general complete. We define $\mathbf{Bord}_n := \widehat{\mathbf{PBord}_n}$ to be its completion. Then \mathbf{Bord}_n is an (∞, n) -category.

Remark 4.4.4. The spaces \mathbf{PBord}_1 and \mathbf{PBord}_2 are complete. However, for $n \geq 6$, \mathbf{PBord}_n is **not** complete; this is because not all invertible cobordisms $M \rightarrow N$ arise from diffeomorphisms $M \rightarrow N$. The **s-cobordism theorem** says that for $n \geq 6$, this statement is equivalent to the vanishing of an invariant of the cobordism known as the **Whitehead torsion**. It's known that for $n \geq 6$ that there are n -bordisms which have nontrivial Whitehead torsion, and hence that \mathbf{PBord}_n is not complete.

4.5 Extra structure on \mathbf{Bord}_n

Most importantly, \mathbf{Bord}_n is a **symmetric monoidal (∞, n) -category**, which means that it has a symmetric monoidal structure (given by the disjoint union) compatible with the (∞, n) structure.

We can also restrict to cobordisms with certain properties: for example there is an (∞, n) -category $\mathbf{Bord}_n^{\text{fr}}$ of framed cobordisms, and an (∞, n) -category $\mathbf{Bord}_n^{\text{or}}$ of oriented cobordisms. Both of these categories also carry a symmetric monoidal structure.

The (∞, n) -category $\mathbf{Bord}_n^{\text{fr}}$ of framed cobordisms will be our focus from now on, since the Cobordism Hypothesis is stated in terms of framed cobordisms.

Note on the constructions The construction of \mathbf{Bord}_n outlined above is similar to Lurie’s definition in [1]. Lurie’s original definition contained an error, and this was corrected by Calaque and Scheimbauer in [2] (which consists mainly of material from [3]) who construct their spaces differently.

They first construct a Segal space of intervals in \mathbb{R}^n and then lift this Segal space structure to \mathbf{PBord}_n . The definitions in [2] correspond roughly to the definitions here by taking our t_j^i to be points in their intervals.

5 Adjoints and dualisability

Given a topological field theory $Z : \mathbf{Bord}_n^{\text{fr}} \rightarrow \mathcal{C}$, we’d like to classify the kind of objects of \mathcal{C} that could be the image of the 0-manifold $*$ under Z . Such objects should satisfy some finiteness condition: for example when $n = 1$ and $\mathcal{C} = \mathbf{Vect}_k$ we saw that $Z(*)$ had to be finite-dimensional, and conversely that any finite-dimensional vector space can be obtained as the image of $*$ under some TFT.

The correct analogue of finite-dimensionality in the ∞ -categorical setting is **full dualisability**, and to define this is the goal of the current section.

It turns out that requiring dualisability for objects is not enough: we’ll also need a notion of dualisability for k -morphisms as well. In the 2-category \mathbf{Cat} we already have a reasonable notion of dualisability for 1-morphisms: a left dual (if it exists) for a functor $F : C \rightarrow D$ should be its left adjoint $G : D \rightarrow C$. We extend this definition to general 2-categories and then to general (∞, n) -categories. Adjoints and duals are very closely related in higher categories.

All of this section is from [1].

5.1 Duals for objects

Recall the following 1-categorical definition:

Definition 5.1.1. Let C be a monoidal category. Let V be an object of C . A **right dual** for V is the data of an object V^\vee and maps

$$\begin{array}{ll} \text{ev} : V \otimes V^\vee \rightarrow 1 & \text{the \textbf{evaluation map}} \\ \text{coev} : 1 \rightarrow V^\vee \otimes V & \text{the \textbf{coevaluation map}} \end{array}$$

such that the triangles¹²

$$\begin{array}{ccc}
 V & & \\
 \text{id}_V \otimes \text{coev} \downarrow & \searrow \text{id}_V & \\
 V \otimes V^\vee \otimes V & \xrightarrow{\text{ev} \otimes \text{id}_V} & V
 \end{array}
 \qquad
 \begin{array}{ccc}
 V^\vee & & \\
 \text{coev} \otimes \text{id}_{V^\vee} \downarrow & \searrow \text{id}_{V^\vee} & \\
 V^\vee \otimes V \otimes V^\vee & \xrightarrow{\text{id}_{V^\vee} \otimes \text{ev}} & V^\vee
 \end{array}
 \quad (1)$$

commute. We also say in this situation that V is a **left dual** of V^\vee .

Remark 5.1.2. If C is symmetric monoidal, then the notions of right dual and left dual coincide and we refer simply to the **dual**.

Example 5.1.3. If C is the symmetric monoidal category \mathbf{Vect}_k (with monoidal structure given by the usual tensor product over k) then a vector space V has a dual if and only if it is finite-dimensional. More specifically, we can always define a space $V^* = \text{Hom}(V, k)$ and an evaluation map $V \otimes_k V^* \rightarrow k$, but we can only define a compatible coevaluation map if V is finite-dimensional.

Proposition 5.1.4. *Left and right duals (if they exist) are unique up to unique isomorphism.*

We can easily extend the definition of a dualisable object to higher categories, by taking the homotopy category.

Definition 5.1.5. Let \mathcal{C} be a symmetric monoidal (∞, n) -category. Say that an object X of \mathcal{C} is **dualisable** if it admits a dual when considered as an object of the homotopy category $h\mathcal{C}$.

If Z is an oriented or framed topological field theory with target \mathcal{C} , then any object X of \mathcal{C} with $X = Z(*)$ must be dualisable since we can obtain X^\vee by evaluating Z on a point with the opposite orientation to that of $*$. In general the condition that X be dualisable is not strong enough for such a TFT to exist. However, for $n = 1$ it turns out that dualisability is sufficient, so this problem will only manifest itself in higher dimensions.

In general we should require that the morphisms in \mathcal{C} should also have duals, which leads us to the notion of adjoints.

5.2 Adjoints in 2-categories

Recall the unit-counit definition of an adjunction:

Definition 5.2.1. Let C, D be two categories and $F : C \rightarrow D$ and $G : D \rightarrow C$ two functors. An **adjunction** between F and G consists of two natural

¹²These triangles are usually presented as pentagons; here we have ignored the associators and the isomorphisms $X \otimes 1 \xrightarrow{\sim} X \xleftarrow{\sim} 1 \otimes X$.

transformations

$$\begin{aligned} u : \text{id}_C &\Rightarrow GF && \text{the } \mathbf{unit} \\ v : FG &\Rightarrow \text{id}_D && \text{the } \mathbf{counit} \end{aligned}$$

such that the following two triangles¹³ commute:

$$\begin{array}{ccc} F \circ \text{id}_C & & \text{id}_C \circ G \\ \text{id}_F \times u \downarrow & \searrow \text{id}_F & \searrow \text{id}_G \\ F \circ G \circ F & \xrightarrow{v \times \text{id}_F} & \text{id}_D \circ F \\ & & G \circ F \circ G \xrightarrow{\text{id}_G \times v} G \circ \text{id}_D \end{array} \quad (2)$$

In this situation we say that F is a **left adjoint** of G and that G is a **right adjoint** of F .

Note that the expression $\eta \times \theta$ means the horizontal composition of the natural transformations η and θ rather than the vertical composition.

Remark 5.2.2. Observe the formal similarity of the triangles of equation (2) to the ones of equation (1). This is a good indication that adjoints are ‘higher duals’.

Proposition 5.2.3. *Adjoints, if they exist, are unique up to unique isomorphism.*

The category **Cat** is the prototypical example of a 2-category: the objects of **Cat** are all (small) categories, the 1-morphisms are functors, and the 2-morphisms are natural transformations. Definition 5.2.1 didn’t really rely on any of the properties of **Cat**, and so we can immediately generalise it to any 2-category:

Definition 5.2.4. Let \mathcal{C} be any 2-category. Let X, Y be objects of \mathcal{C} and let $F : X \rightarrow Y$ and $G : Y \rightarrow X$ be two 1-morphisms. Say that a 2-morphism $u : \text{id}_X \rightarrow G \circ F$ is the **unit of an adjunction between F and G** if there exists another 2-morphism $v : F \circ G \rightarrow \text{id}_Y$ such that the following two triangles commute:

$$\begin{array}{ccc} F \circ \text{id}_X & & \text{id}_X \circ G \\ \text{id}_F \times u \downarrow & \searrow \text{id}_F & \searrow \text{id}_G \\ F \circ G \circ F & \xrightarrow{v \times \text{id}_F} & \text{id}_Y \circ F \\ & & G \circ F \circ G \xrightarrow{\text{id}_G \times v} G \circ \text{id}_Y \end{array}$$

In this case we say that v is the **counit**, and that F (resp. G) is **left** (resp. **right**) adjoint to G (resp. F).

¹³Once again, these triangles are really pentagons. If we think of **Cat** as a strict 2-category, then they are squares since we don’t need any associators.

Remark 5.2.5. If u is the unit of an adjunction, then a compatible counit v is uniquely determined, and vice versa. So it's enough to specify the existence of either u or v .

Example 5.2.6. A category with a single object is the same thing as a monoid. Similarly if \mathcal{C} is a 2-category with a single object $*$ then the category $\text{Hom}_{\mathcal{C}}(*, *)$ is a monoidal category.

Conversely if M is a monoidal category then we can build a 2-category $\mathcal{B}M$ with a single object $*$, hom-category $\text{Hom}_{\mathcal{B}M}(*, *) \cong M$ and composition law for 1-morphisms given by the tensor product on M .

Then an object X of M is right dual to an object Y of M if and only if it is right adjoint to Y when both are considered as 1-morphisms of $\mathcal{B}M$. We often call $\mathcal{B}M$ the **delooping** of M .

Adjointness are closely related to invertibility:

Proposition 5.2.7. *Let \mathcal{C} be a 2-category in which every 2-morphism is invertible. Let f be a 1-morphism of \mathcal{C} . Then the following are equivalent:*

- i) f is invertible.*
- ii) f admits a left adjoint.*
- iii) f admits a right adjoint.*

Definition 5.2.8. Say that a 2-category \mathcal{C} **has adjoints for 1-morphisms** if every 1-morphism has both a left and a right adjoint.

5.3 Adjoints in higher categories

We'd like to generalise Definition 5.2.4 from 2-categories to higher categories.

Definition 5.3.1. Let $n \geq 2$ and let \mathcal{C} be an (∞, n) -category. Let $h_2\mathcal{C}$ be the **homotopy 2-category** of \mathcal{C} , with

$$\begin{aligned} \text{objects} &\longleftrightarrow \text{objects of } \mathcal{C} \\ \text{1-morphisms} &\longleftrightarrow \text{1-morphisms of } \mathcal{C} \\ \text{2-morphisms} &\longleftrightarrow \text{isomorphism classes of 2-morphisms of } \mathcal{C} \end{aligned}$$

Remark 5.3.2. **Homotopy n -categories** are defined similarly.

Definition 5.3.3. Let \mathcal{C} be an (∞, n) -category. Say that \mathcal{C} **has adjoints for 1-morphisms** if $h_2\mathcal{C}$ has adjoints for 1-morphisms. More generally, for $1 < k < n$ say that \mathcal{C} **has adjoints for k -morphisms** if for any two objects X, Y of \mathcal{C} the $(\infty, n-1)$ -category $\text{Map}(X, Y)$ has adjoints for $(k-1)$ -morphisms. Say that \mathcal{C} **has adjoints** if it has adjoints for k -morphisms for all $0 < k < n$.

Remark 5.3.4. If every k -morphism in \mathcal{C} is invertible then \mathcal{C} has adjoints for k -morphisms. The converse is true provided that all $(k + 1)$ -morphisms are invertible - this is a consequence of Proposition 5.2.7.

Remark 5.3.5. The condition that \mathcal{C} have adjoints depends on the choice of n . If we regard \mathcal{C} as an $(\infty, n + 1)$ -category with all $(n + 1)$ -morphisms invertible then in general \mathcal{C} does not have adjoints for n -morphisms unless it is an ∞ -groupoid.

If \mathcal{C} is monoidal then we can ask for a bit more:

Definition 5.3.6. Let \mathcal{C} be a monoidal (∞, n) -category. Say that \mathcal{C} **has duals** if the following two conditions are satisfied:

- i) Every object X has both a left and a right dual when considered as an object of the homotopy category $h\mathcal{C}$.¹⁴
- ii) \mathcal{C} has adjoints.

Remark 5.3.7. We can generalise our earlier construction of Example 5.2.6. If \mathcal{C} is a monoidal (∞, n) -category then it is possible to build an $(\infty, n + 1)$ -category \mathcal{BC} (the **delooping** of \mathcal{C}) with a single object $*$, recovering \mathcal{C} as the mapping object $\text{Hom}_{\mathcal{BC}}(*, *)$. Then \mathcal{C} has duals if and only if \mathcal{BC} has adjoints.

5.4 Full dualisability

Given a symmetric monoidal (∞, n) -category we'd like to pick out the largest subcategory with duals.

Theorem 5.4.1. *Let \mathcal{C} be a symmetric monoidal (∞, n) -category. Then there exists another symmetric monoidal (∞, n) -category \mathcal{C}^{fd} with duals, and a symmetric monoidal functor $i : \mathcal{C}^{\text{fd}} \rightarrow \mathcal{C}$, universal among symmetric monoidal functors $j : \mathcal{D} \rightarrow \mathcal{C}$ where \mathcal{D} has duals.*

Remark 5.4.2. \mathcal{C}^{fd} is determined up to equivalence by the above properties. In general we can obtain \mathcal{C}^{fd} from \mathcal{C} by repeatedly discarding morphisms that don't admit adjoints (and objects that don't admit duals).

Example 5.4.3. If \mathcal{C} is a symmetric monoidal $(\infty, 1)$ -category then \mathcal{C}^{fd} is equivalent to the full subcategory of \mathcal{C} spanned by the dualisable objects.

Definition 5.4.4. Say that an object X of \mathcal{C} is **fully dualisable** if it belongs to the essential image¹⁵ of the functor i .

Example 5.4.5. For each $n > 0$, the (∞, n) -category $\mathbf{Bord}_n^{\text{fr}}$ has duals. Every k -morphism can be identified with an oriented manifold M ; the morphism \bar{M} (M with the opposite orientation) is both a left and a right adjoint to M .

¹⁴Note that $h\mathcal{C}$ inherits its monoidal structure from \mathcal{C} . If \mathcal{C} is symmetric monoidal then this condition is the condition that every object be dualisable.

¹⁵Recall that the **essential image** of a functor $F : \mathcal{D} \rightarrow \mathcal{E}$ is the smallest isomorphism-closed subcategory of \mathcal{E} containing the image of F .

Example 5.4.6. If \mathcal{C} is the $(\infty, 1)$ -category \mathbf{Vect}_k , then an object of \mathcal{C} is fully dualisable if and only if it is finite-dimensional.

This generalises to the following:

Proposition 5.4.7. *An object of a symmetric monoidal $(\infty, 1)$ -category is fully dualisable if and only if it is dualisable.*

In general full dualisability is a much stronger condition than dualisability! In dimension 2, there are some simple criteria for testing whether or not an object is fully dualisable:

Proposition 5.4.8. *Let \mathcal{C} be a symmetric monoidal $(\infty, 2)$ -category. Let X be an object of \mathcal{C} . Then X is fully dualisable if and only if it admits a dual X^\vee and the evaluation map $\text{ev} : X \otimes X^\vee \rightarrow 1$ has both a left and a right adjoint.*

6 The Cobordism Hypothesis

In this short section we rigourously state the Cobordism Hypothesis. We begin with some bookkeeping.

6.1 Terminology

Definition 6.1.1. An (∞, n) -**functor** between two (∞, n) -categories \mathcal{C} and \mathcal{D} is a map of the underlying simplicial spaces (which is itself a natural transformation between the defining functors).

Theorem 6.1.2. *The collection $\text{Fun}(\mathcal{C}, \mathcal{D})$ of (∞, n) -functors between two (∞, n) -categories itself forms an (∞, n) -category.*

Remark 6.1.3. The collection of all (small) (∞, n) -categories naturally forms an $(\infty, n + 1)$ -category with mapping objects $\text{Map}(\mathcal{C}, \mathcal{D}) = \text{Fun}(\mathcal{C}, \mathcal{D})$.

Proposition 6.1.4. *We can also define **symmetric monoidal (∞, n) -functors** between symmetric monoidal (∞, n) -categories. The collection of symmetric monoidal (∞, n) -functors between two symmetric monoidal (∞, n) -categories \mathcal{C} and \mathcal{D} itself forms an (∞, n) -category, which we refer to as $\text{Fun}^\otimes(\mathcal{C}, \mathcal{D})$.*

Definition 6.1.5. A **fully extended framed n -dimensional topological field theory** is a symmetric monoidal (∞, n) -functor with source $\mathbf{Bord}_n^{\text{fr}}$. The collection of all fully extended framed n -TFTs with target \mathcal{C} is the (∞, n) -category $\text{Fun}^\otimes(\mathbf{Bord}_n^{\text{fr}}, \mathcal{C})$.

Definition 6.1.6. Given an (∞, n) -category \mathcal{C} , I will denote the underlying $(\infty, 0)$ -category¹⁶ of \mathcal{C} by $\pi_{\leq \infty}(\mathcal{C})$. This notation is not standard.

¹⁶a.k.a. ∞ -groupoid

6.2 A Precise Statement

Claim 6.2.1 (the Cobordism Hypothesis). *If \mathcal{C} is a symmetric monoidal (∞, n) -category then the evaluation functor $Z \mapsto Z(*)$ induces an equivalence*

$$\mathrm{Fun}^{\otimes}(\mathbf{Bord}_n^{\mathrm{fr}}, \mathcal{C}) \xrightarrow{\simeq} \pi_{\leq \infty}(\mathcal{C}^{\mathrm{fd}})$$

In particular, the Cobordism Hypothesis states that $\mathrm{Fun}^{\otimes}(\mathbf{Bord}_n^{\mathrm{fr}}, \mathcal{C})$ is an ∞ -groupoid, and hence a topological space. We can think of it as a classifying space for fully dualisable objects in \mathcal{C} .

It is not too difficult to prove that $\mathrm{Fun}^{\otimes}(\mathbf{Bord}_n^{\mathrm{fr}}, \mathcal{C})$ is an ∞ -groupoid. The hard part of proving the Cobordism Hypothesis is proving that the induced functor is an equivalence. A sketch proof of this is given by Lurie in [1].

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